



National  
Center  
for  
Rural  
Road  
Safety

## Improving Rural Road Safety with the Safe System Approach



## A 6-part Webinar Series

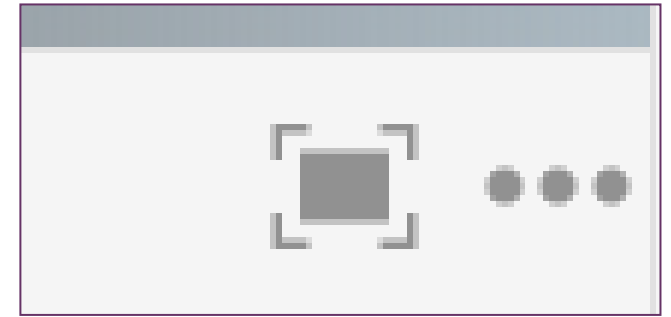
## Part 3: Safe Vehicles

Presented by:

- Eric Jackson PhD, Executive Director, Connecticut Transportation Institute, Director, Connecticut Transportation Safety Research Center
- Tyler Weldon, State Maintenance Engineer, Colorado DOT
- Randy Johnson, KC Scout Manager, Missouri DOT



# Webinar Logistics



- Duration is 11:00 AM - 12:30 PM Mountain
- Webinar – recorded and archived on website. For quality of recording, phone will be muted during presentation
- If listening on the phone, please mute your computer
- To maximize the presentation on your screen, click the “window box” in the top right of the presentation
- At the end of each section, there will be time for Q&A
- There is a handout pod at the bottom of the screen
- Please complete follow-up surveys; they are vital to assessing the webinar quality





# Certificates of Completion/CEUs

Survey Link –

<https://lp.constantcontactpages.com/sv/48DCGTk>

- Survey closes 2 weeks after webinar
- Expect certificate/CEU form approx. 4-6 weeks after webinar
- Return CEU form to [ContinuingEd@montana.edu](mailto:ContinuingEd@montana.edu) **NOT** Rural Safety Center
- Request a verification of completion form





# Today's Presenters



Eric Jackson PhD  
Executive Director  
Connecticut  
Transportation Institute



Tyler Weldon  
State Maintenance  
Engineer  
Colorado DOT



Randy Johnson  
KC Scout Manager  
Missouri DOT



# Goals of this Webinar

Once you have completed this webinar, you will have:

an understanding of the Safe Vehicle element in the Safe System Approach through the lens of actions agencies can take.



# Learning Outcomes

To achieve the webinar goal, you will learn to:

Explain how connected and automated vehicles work and list actionable items you can take to prepare for automated, connected, and electric vehicles in rural areas.

Name the benefits of using an autonomous attenuator truck in rural areas.

Define how a real-time digital warning system works.



# National Safety Efforts: Intertwining Concepts

## Foundation



## Framework



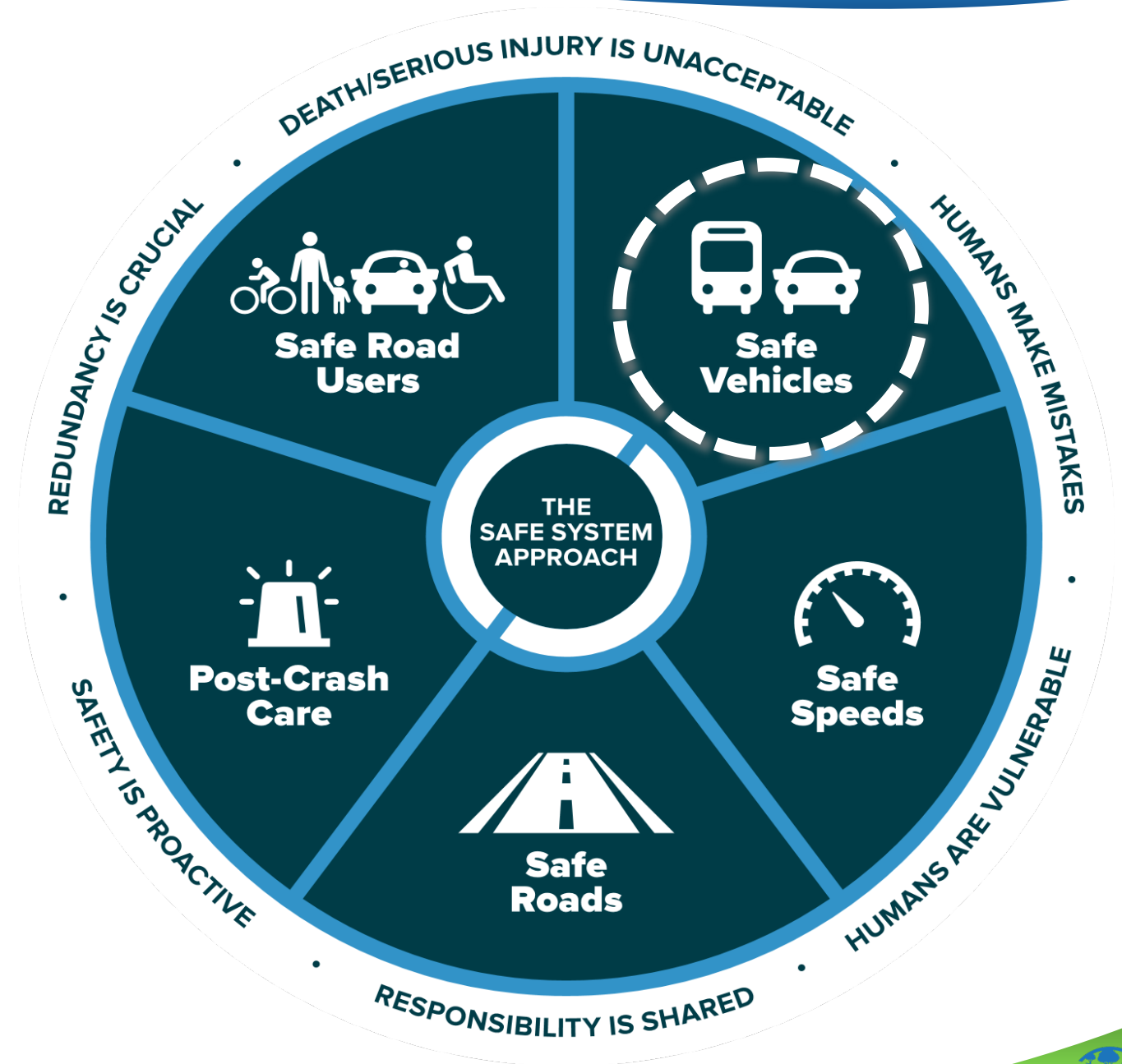
## Goal





## Safe System:

- Holistic Approach
- Aims to eliminate fatal and serious injuries for all road users
- 5 Elements
- 6 Principles





Eric Jackson PhD  
Executive Director  
Connecticut Transportation  
Institute



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Center  
for  
Rural  
Road  
Safety

Explain how connected and automated vehicles work and list actionable items you can take to prepare for automated, connected, and electric vehicles in rural areas.

Name the benefits of using an autonomous attenuator truck in rural areas.

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## Terms to Know?

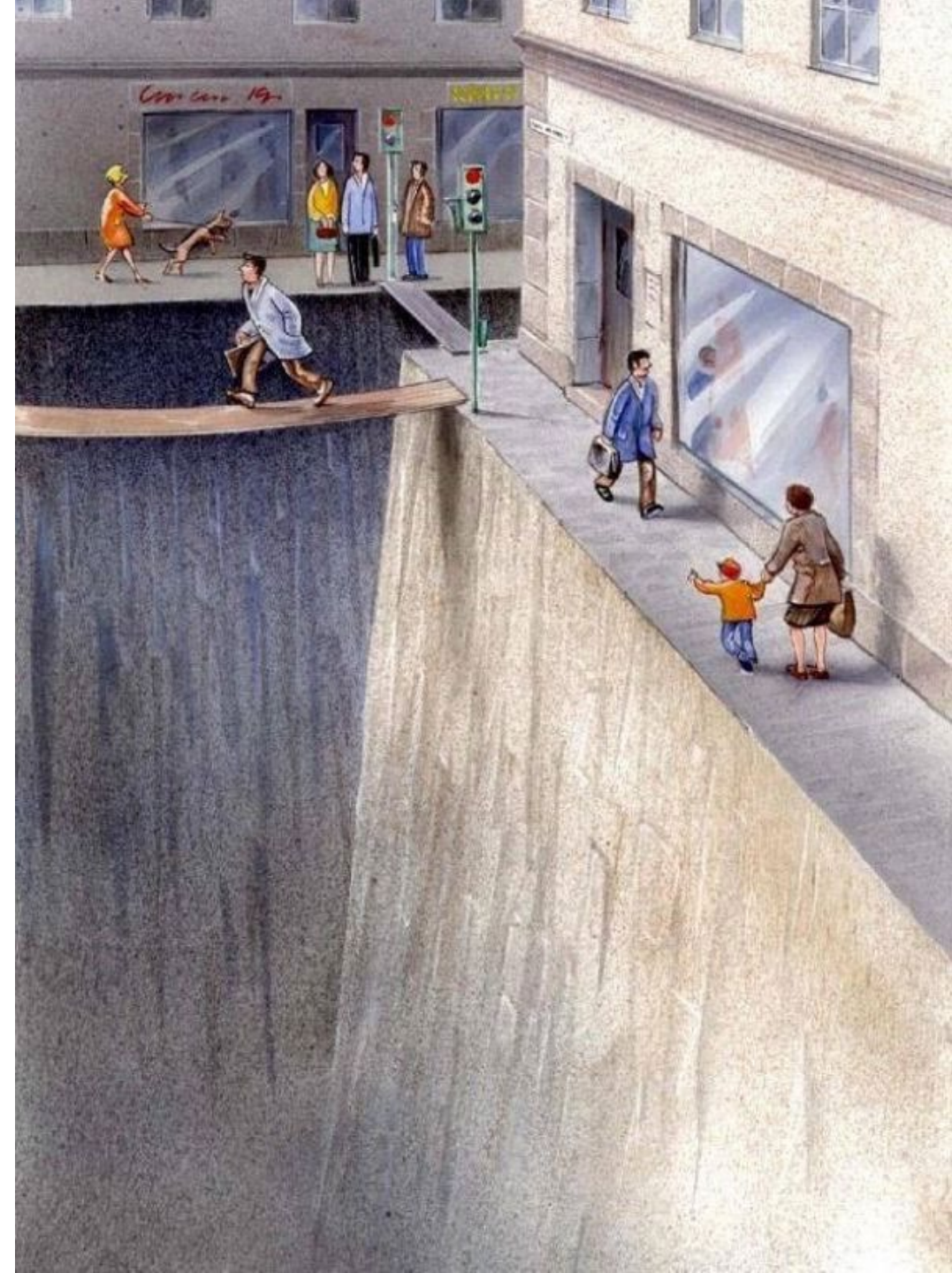
- Autonomous
- Automated
- Connected
- LIDAR (Light Detection and Ranging)

# Motivation

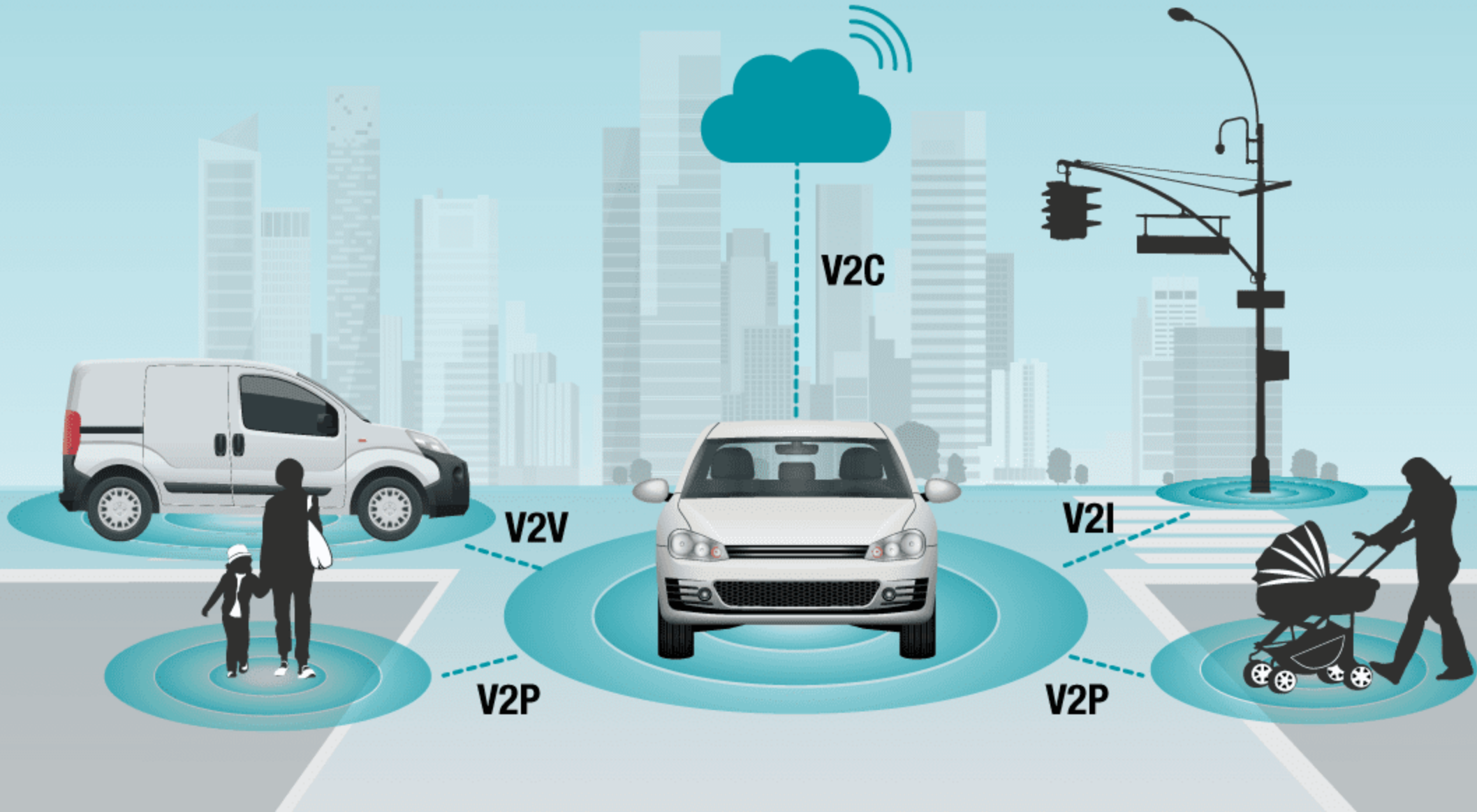


# Where Have We Been? Where Are We Headed?

- What is an AV and how do they work?
- How far away are AVs?
- What are some of the challenges?
- How will this technology change our lives?
- Will you own one?



# Connected



# Automated





Autonomous

# The route to the autonomous car

Frank J. Goguen, CFA<sup>®</sup>, senior research analyst and John D. Connolly, writer at The Boston Company Asset Management LLC<sup>®</sup> explore the future economic and social potential of driverless cars.

THE BOSTON COMPANY  
ASSET MANAGEMENT, LLC

## Advantages

Safety  
**90%**

of road traffic accidents are currently caused by human error.<sup>1</sup>

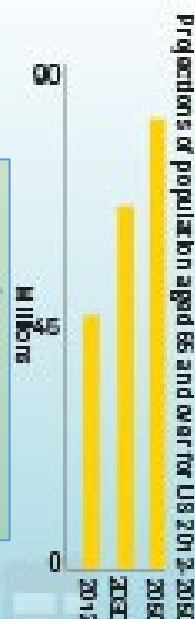
Driverless cars could translate into approximately

**36,000** lives saved each year

and approximately **US\$ 488 billion.**

Social  
Greater mobility provided to elderly and disabled people.

People over the age of 65 expected to double in US by **2050.**<sup>2</sup>



Economic  
Morgan Stanley estimates Autonomous cars will result in **US\$ 1.3 trillion** savings every year for the US economy, globally this translates into **US\$ 5.6 trillion.**<sup>3</sup>

Economic benefits for drivers

- Fuel costs
- Productivity gains
- Accident costs

## Potential obstacles

**Liability**  
Who accepts responsibility in the case of an accident?

**Legislation**  
US infrastructure deficiencies mean that **US\$ 10.8 billion** had to be found to keep the Highway Trust Fund solvent until May 2015.<sup>4</sup>

## Consumer adoption

Once people accept and trust the systems, adoption rates are expected to climb.

**Welcome to the autonomous car**



**2030**

# AUTOMATION LEVELS OF AUTONOMOUS CARS

## LEVEL 0



There are no autonomous features.

## LEVEL 1



These cars can handle one task at a time, like automatic braking.

## LEVEL 2



These cars would have at least two automated functions.

## LEVEL 3



These cars handle “dynamic driving tasks” but might still need intervention.

## LEVEL 4

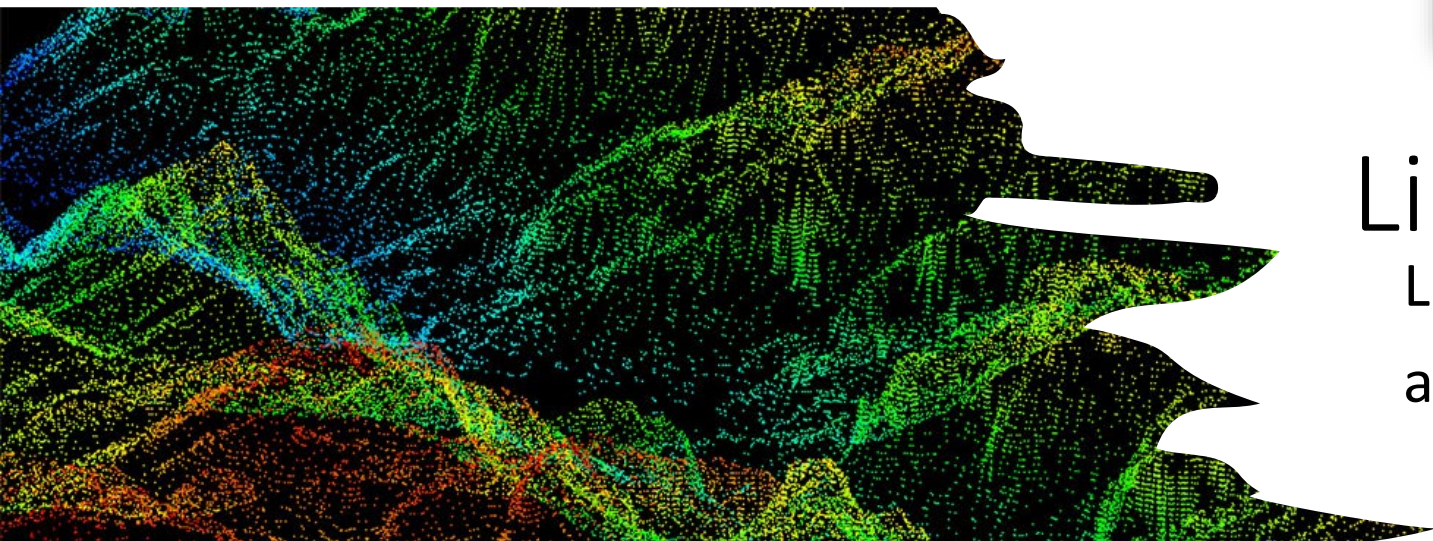
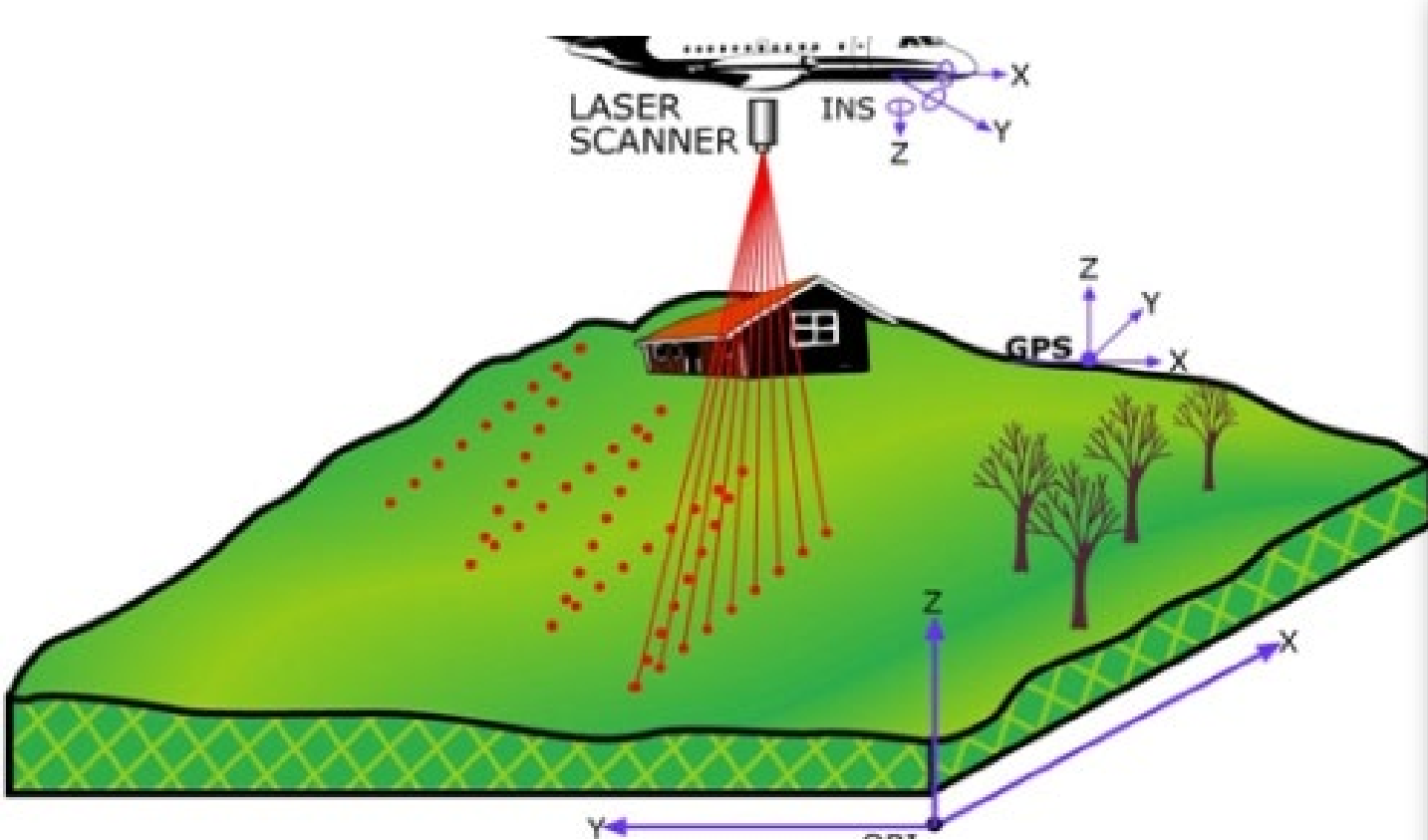


These cars are officially driverless in certain environments.

## LEVEL 5



These cars can operate entirely on their own without any driver presence.



## Under the bonnet

How a self-driving car works

Signals from **GPS (global positioning system)** satellites are combined with readings from tachometers, altimeters and gyroscopes to provide more accurate positioning than is possible with GPS alone

**Lidar (light detection and ranging)** sensors bounce pulses of light off the surroundings. These are analysed to identify lane markings and the edges of roads

**Video cameras** detect traffic lights, read road signs, keep track of the position of other vehicles and look out for pedestrians and obstacles on the road

**Radar sensor**

**Ultrasonic sensors** may be used to measure the position of objects very close to the vehicle, such as curbs and other vehicles when parking

The information from all of the sensors is analysed by a **central computer** that manipulates the steering, accelerator and brakes. Its software must understand the rules of the road, both formal and informal

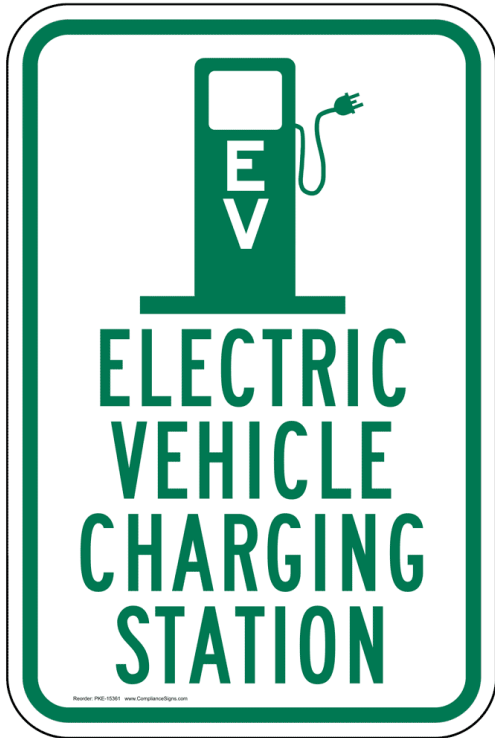
**Radar sensors** monitor the position of other vehicles nearby. Such sensors are already used in adaptive cruise-control systems

Source: *The Economist*

# LiDAR

Light Detection  
and Ranging





# HOW UBER'S FIRST SELF-DRIVING CAR WORKS

Top mounted **LIDAR** beams 1.4 million laser points per second to create a 3D map of the car's surroundings.

There are **20 cameras** looking for braking vehicles, pedestrians, and other obstacles.

A **colored camera** puts LiDAR map into color so the car can see traffic light changes.

**Antennae** on the roof rack let the car position itself via GPS.



**LIDAR modules** on the front, rear, and sides help detect obstacles in blind spots.

A **cooling system** in the car makes sure everything runs without overheating.

VOLVO

## Electrification

### Our future is electric

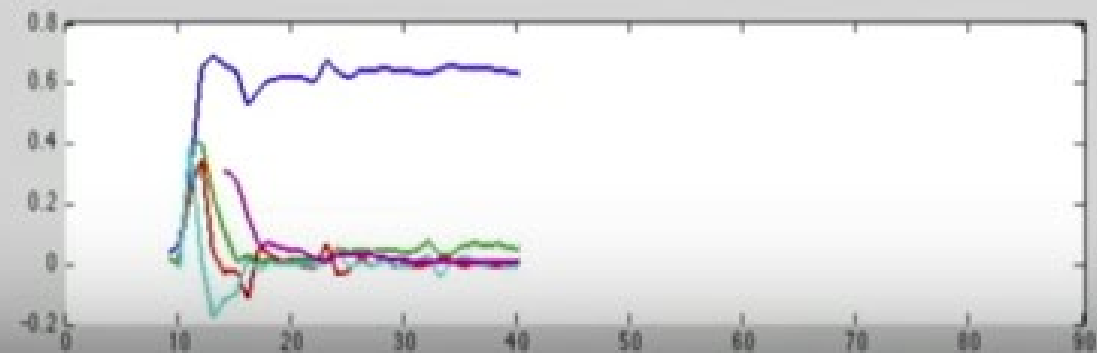
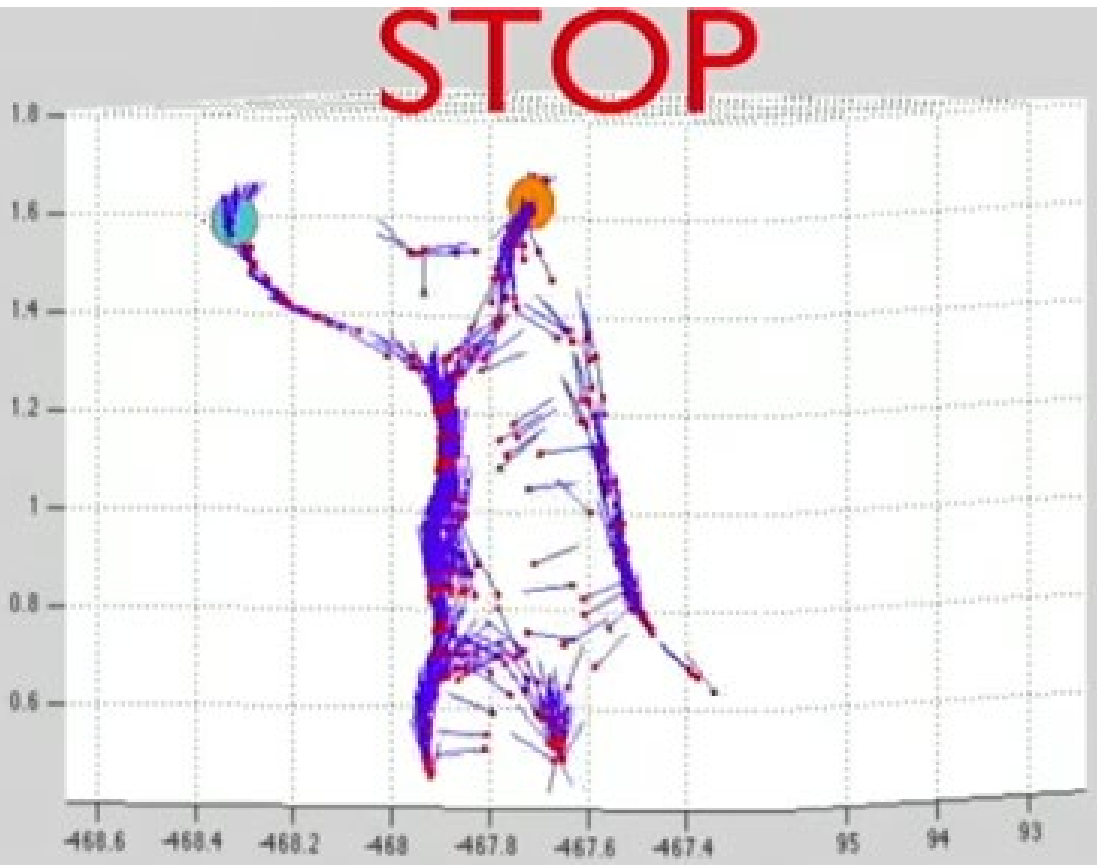
Discover our Recharge pure electric and plug-in hybrid cars – designed for a better drive and the vision of a climate neutral future. And if charging is not an option, explore our mild hybrids.



SOURCE: Uber

BUSINESS INSIDER

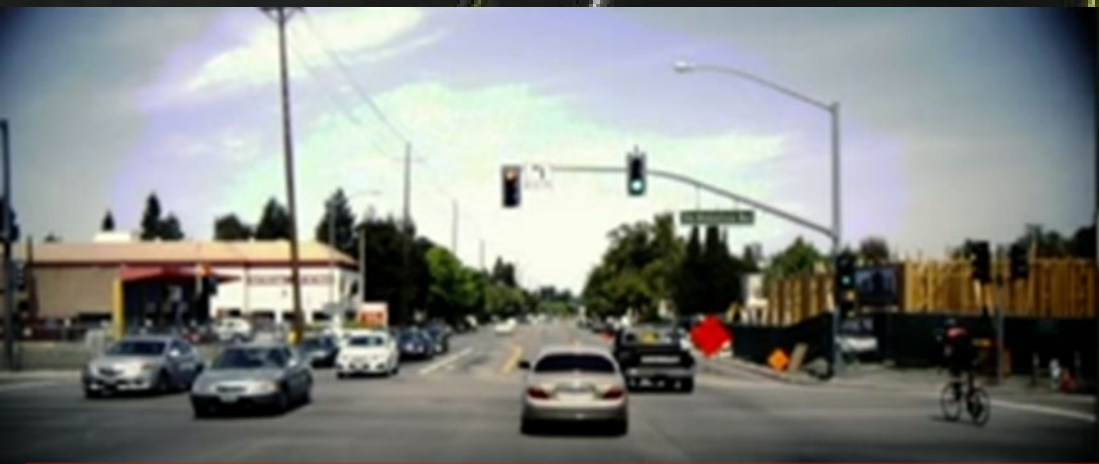
# How do AVs “See”

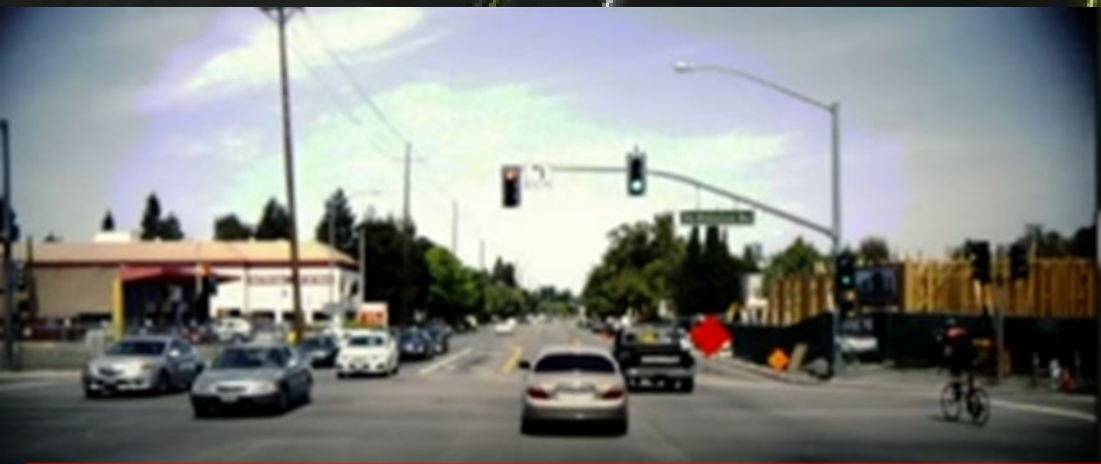
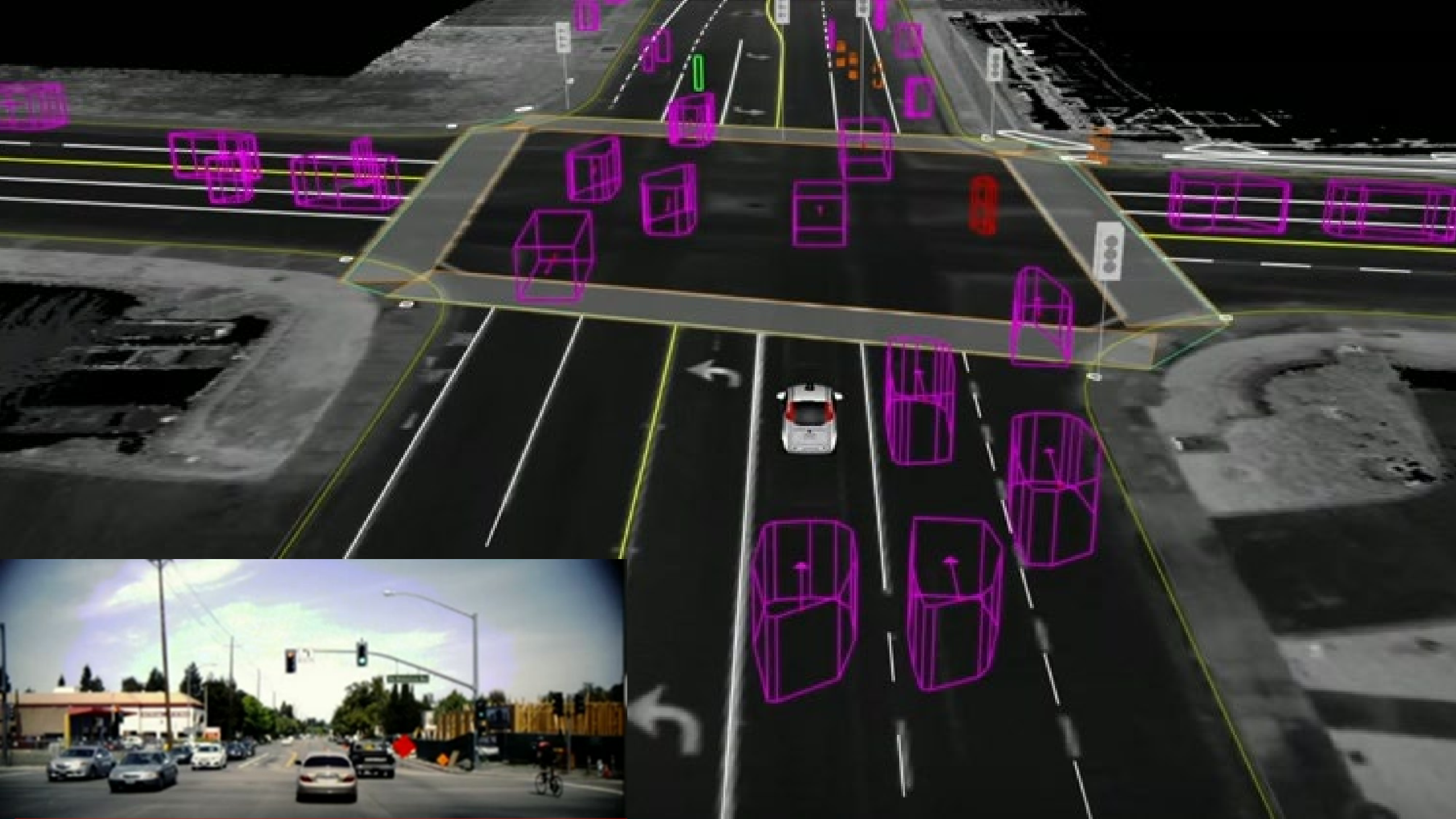


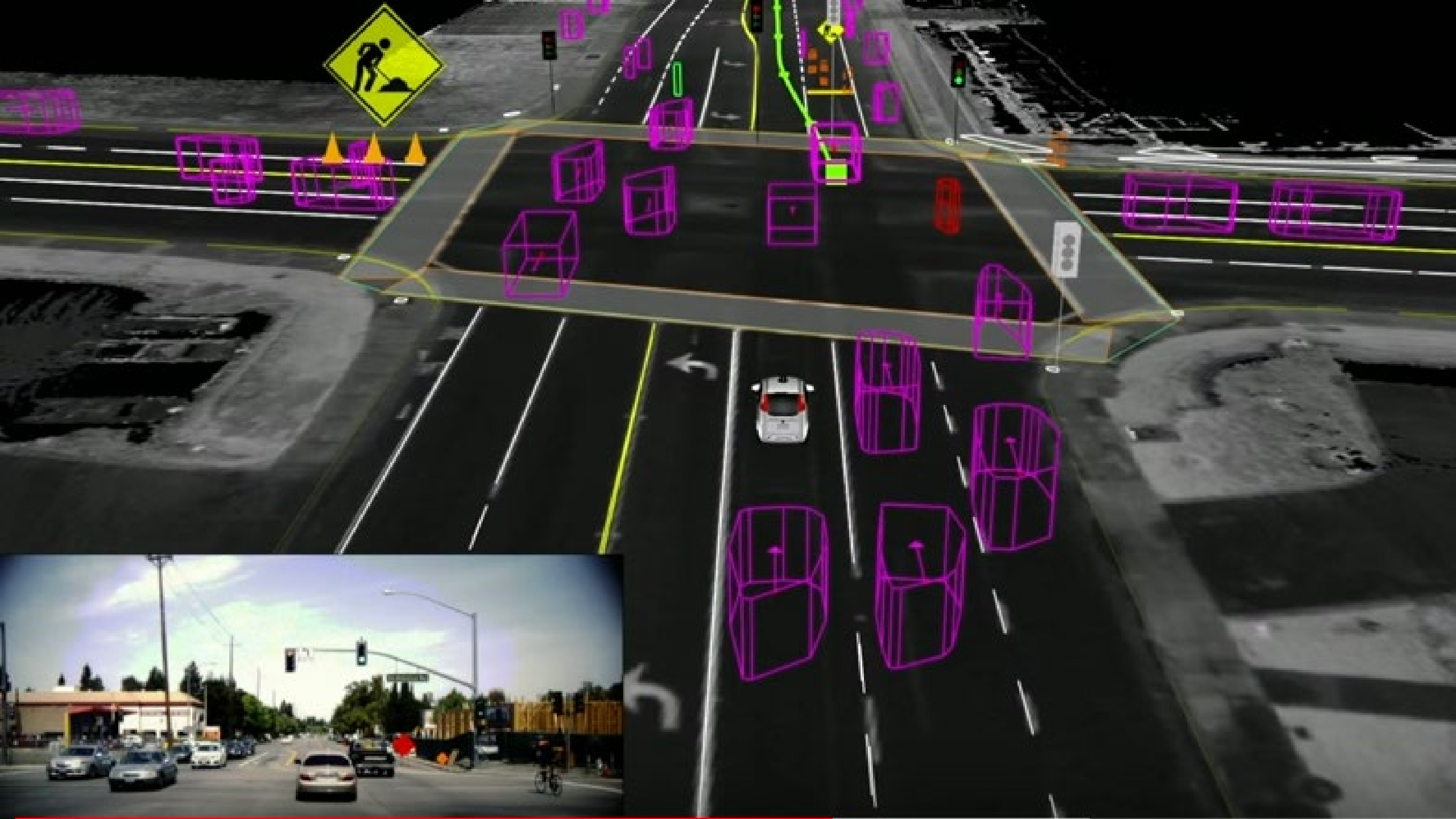


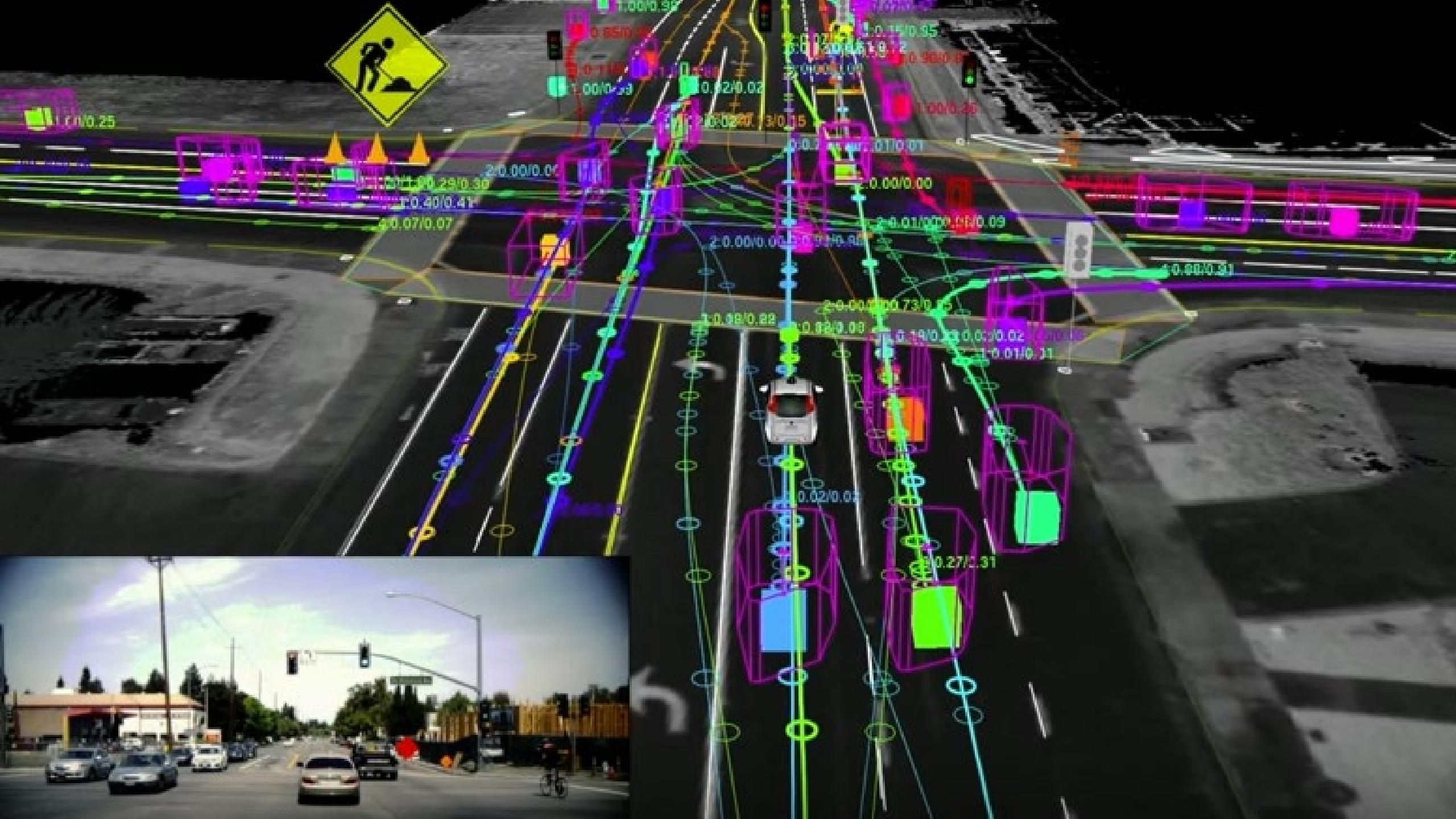
# View From the Camera of the Car

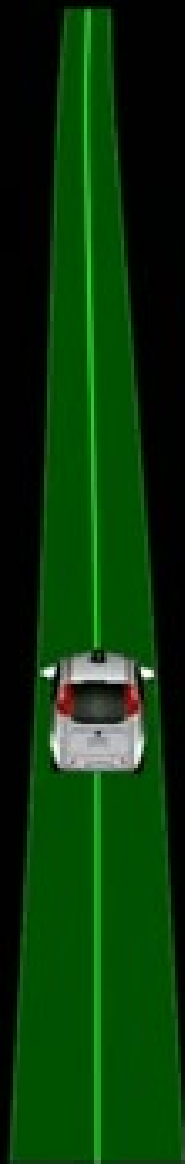


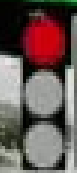
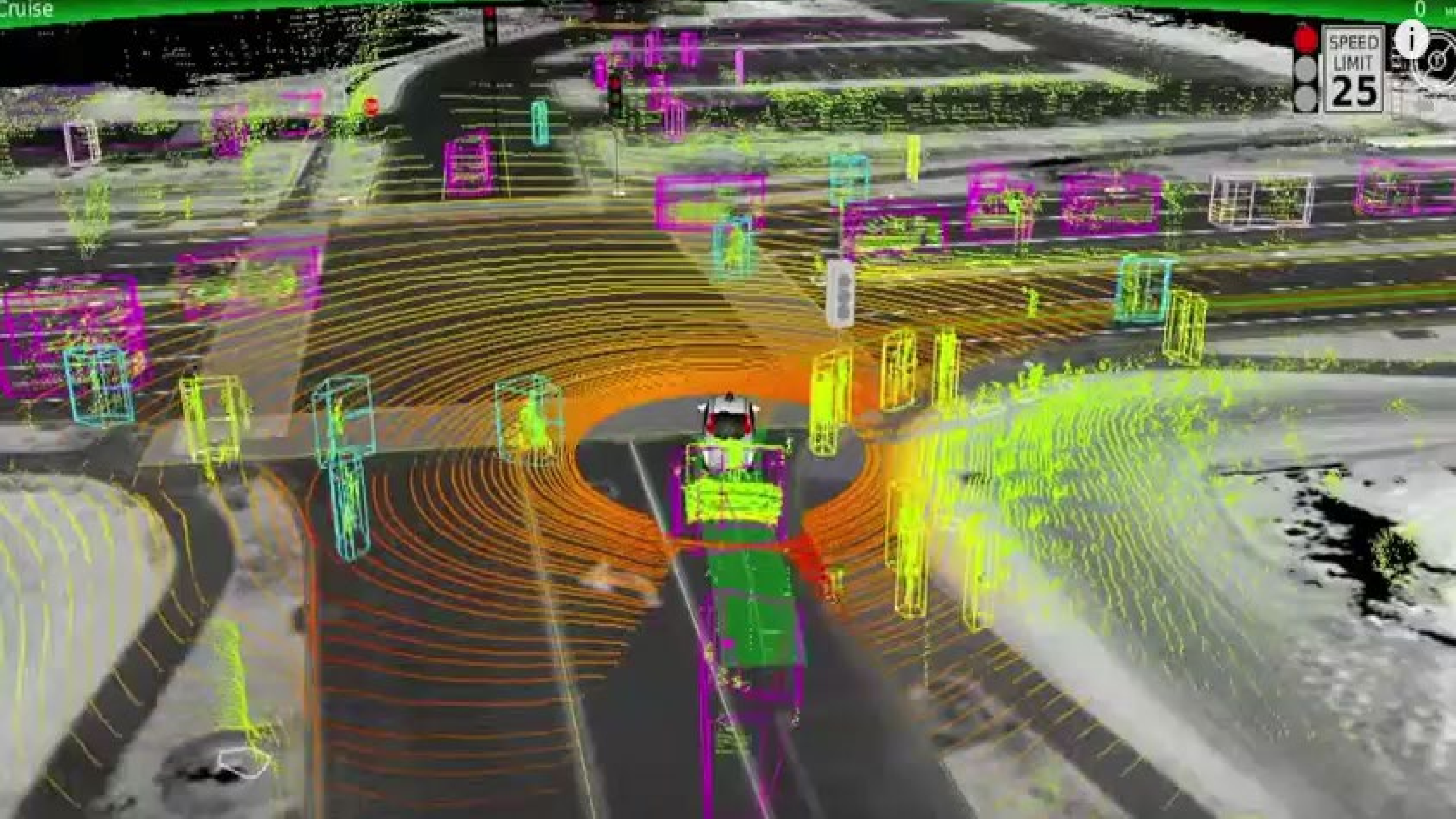










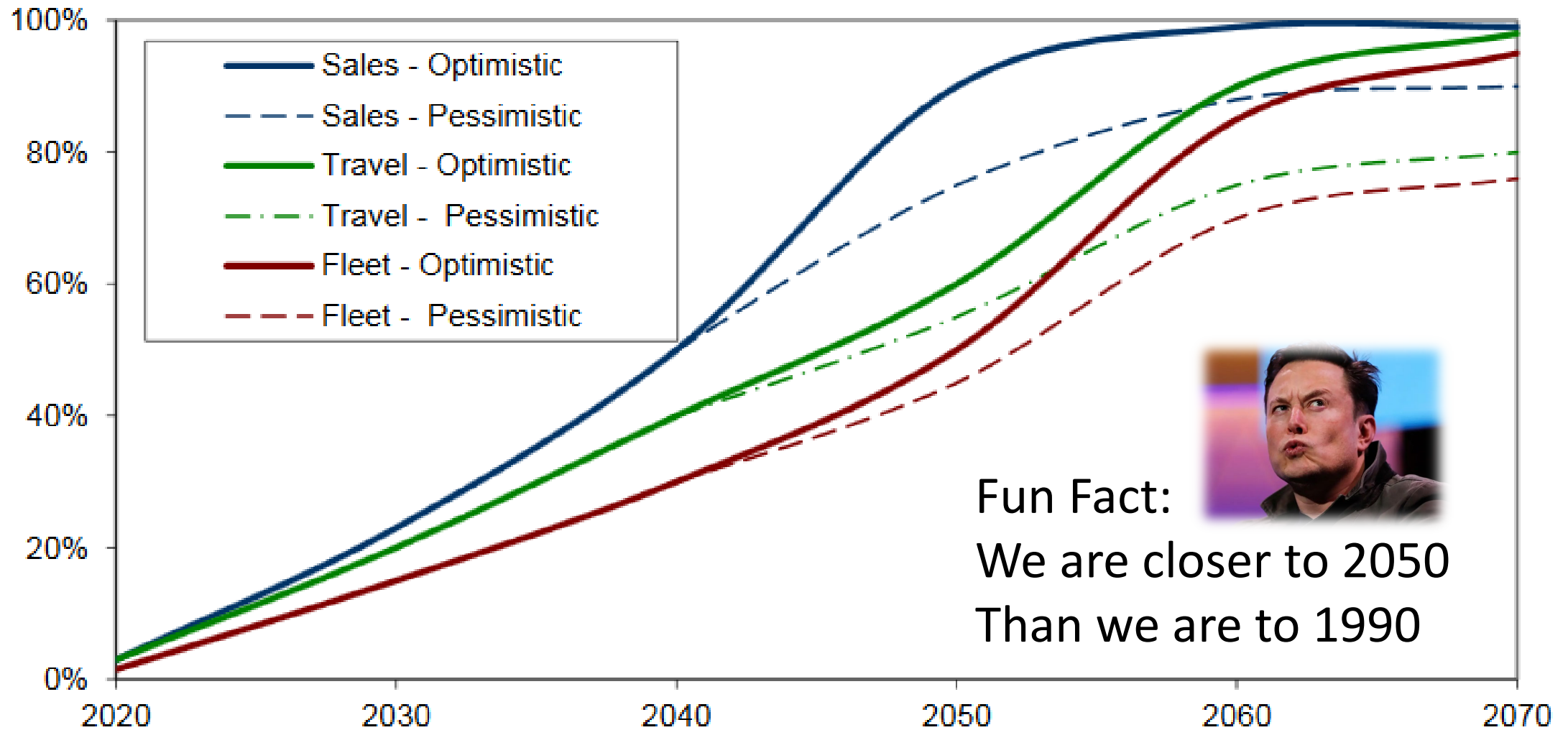


SPEED  
LIMIT  
25



# Timeline

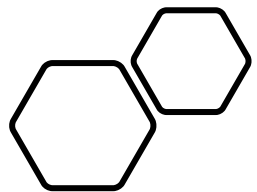
**Exhibit 15** Autonomous Vehicle Sales, Fleet and Travel Projections



Fun Fact:

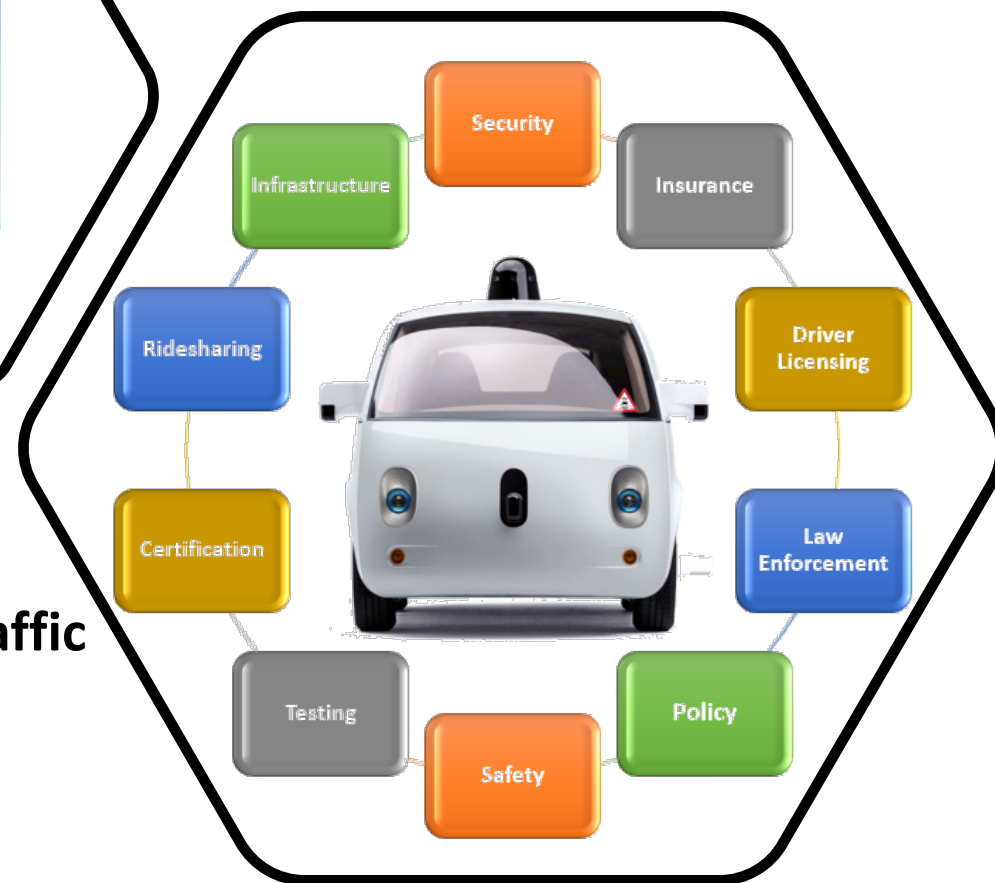


We are closer to 2050  
Than we are to 1990



# What Challenges Exist?

- Driving safely despite unclear lane markings
- Reliably recognizing traffic lights that are not working
- Making left turns into intersections with fast-moving traffic
- Detecting which small objects in the roadway must be avoided
- The ability to operate safely in all weather conditions
- [Cybersecurity](#). There is no evidence yet that autonomous cars will be any more secure than any other networked computers.



# Rural Areas Action Items

- Install and maintain lane markings
- Accurate mapping of roads
- Electric vehicle charging infrastructure
- Uniform signage that is MUTCD compliant, retroreflective and visible
- Evaluation of “non-engineered” roadways (horizontal and vertical curvature)
- Teslas are coming



# Prepare your Workforce

## What Will be Required of the Workforce of the Future?



Tech Brief Series

Tech Brief - 2018-2

### Connected & Autonomous Vehicles

With a host of new vehicle technologies emerging, it's common to see news articles discussing automated and connected vehicle technologies. Though at times these terms are mistakenly used interchangeably, there is a clear distinction between the two concepts. This technical brief provides an overview of the two technologies.

#### Connected Vehicles

In the simplest sense, connected vehicle (CV) technologies are tools that allow vehicles to communicate with each other and with the world around them. This communication in turn allows drivers to make decisions using information from the surrounding environment. One should note that while using CV technologies, human drivers are still in control of the vehicle.

Connected vehicles may seem like a futuristic concept, but the average driver is already familiar with CV technology in the form of dynamic routing using GPS navigation via the cellular network. Information regarding collisions, active construction and other congestion along a route are communicated to the driver using visual and audio displays, either in the vehicle or on a mobile phone. This information then allows the driver to make an informed decision regarding the best route to take. In the future, connected vehicle technologies may include those shown in the graphic below.



Courtesy Qualcomm

When talking about connected vehicle technologies, the terms V2V, V2I, V2P and V2X are often used. As show in the graphic below, V2V refers to vehicles talking to each other, V2P refers to vehicles talking to pedestrians, and V2I refers to vehicles talking to infrastructure surrounding them.



Courtesy Intellis

One of the biggest issues surrounding CV technologies is ensuring a secure communications network. The Federal Communications Commission (FCC) set aside bandwidth specifically for intelligent transportation systems communication using dedicated short-range communication (DSRC), which is a specialized form of WiFi. A security credential management system (SCMS) for messages sent over DSRC will be tested as part of national connected vehicle pilot deployment projects currently underway in New York City, Tampa and Wyoming.

In the municipal realm, the National Operations Center for Excellence, a partnership of AASHTO, ITE and ITSA with support from FHWA, issued the SPaT Challenge to local agencies. The SPaT Challenge is to implement DSRC and transmit Signal Phasing and Timing (SPaT) data along a corridor in each of the 50 states by 2020. So far 26 states have committed to respond to the SPaT Challenge, with 216 signals currently in operation and 2,121 planned. Look for more in-depth information on the SPaT Challenge in future tech briefs.



Courtesy NOCoE



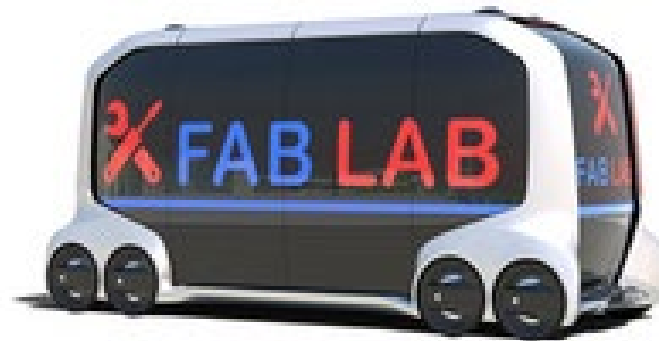
## Benefits for Rural Areas

- Rural roadways experience a greater number of fatal crashes than urban roadways.
  - Curve Speed Warnings
  - Work Zone Warnings and Crash Alerts
  - Stop Sign Gap Assistance
  - Do Not Pass Warning
  - Maintained mobility for aging population
  - Increased mobility for disabled or younger individuals
  - Reduced need for vehicle ownership



What does the future of AV look like?





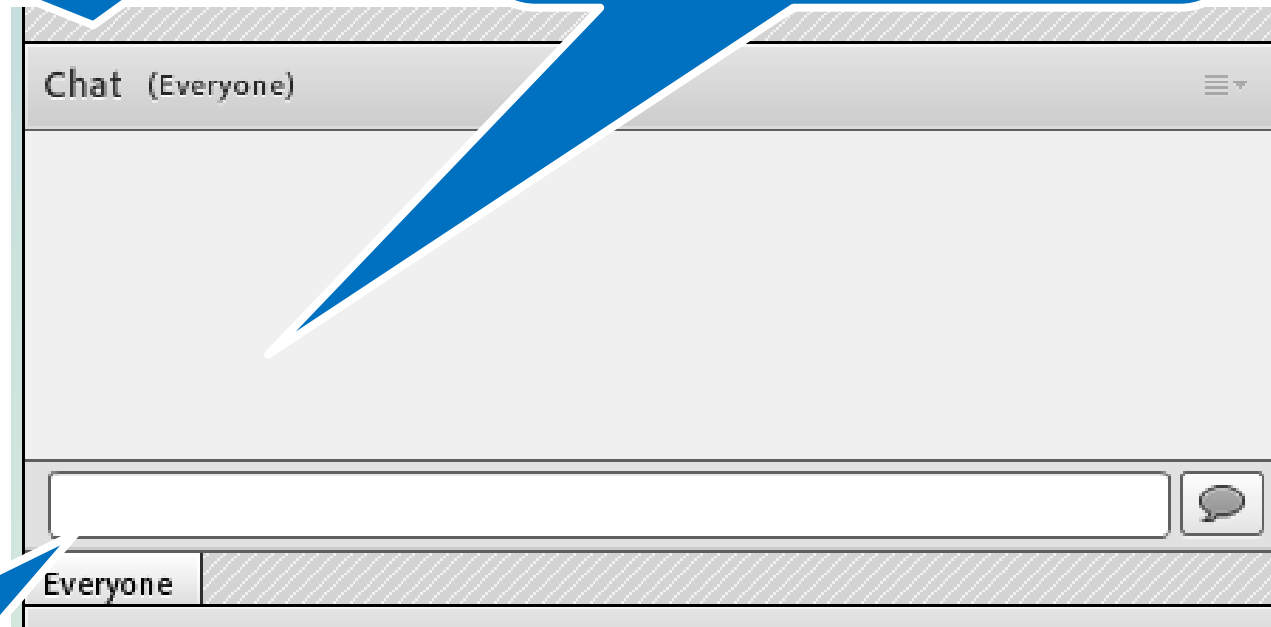


## Directing Your Questions via the Chat Pod

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Tyler Weldon  
State Maintenance Engineer  
Colorado DOT



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Explain how connected and automated vehicles work and list actionable items you can take to prepare for automated, connected, and electric vehicles in rural areas.

Name the benefits of using an autonomous attenuator truck in rural areas.

Define how a real-time digital warning system works.

# *Tools for Tomorrow, Here Today*



**COLORADO**  
Department of Transportation

## CDOT Autonomous TMA Truck (ATMA)

Developed By

**KRATOS**  
UNMANNED SYSTEMS DIVISION

**Royal**  
TRUCK & EQUIPMENT INC.



RSC Webinar September 29 2021

# CDOT Organization

- Maintain 23,000 lane miles of highways
- Maintenance of pavement, bridges, tunnel and pavement markings
- 1800 Maintenance Employees and 279 Patrols
- Highway Maintenance Degree Program at Front Range CC.



# Project Vision

- Remove driver from TMA truck
- Decrease risk of operations
- Increase efficiency of operations
- Pursue cutting-edge technology to improve highway management



# Project Goals



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1. Installation of system on CDOT piece of equipment
2. Identification of limitations and anomalies in track setting
3. Log open highway miles in striping operation
4. Interchangeability of lead vehicle – sweeper or mower
5. Expand Program



# Traffic Mobile Attenuator - TMA



**COLORADO**  
Department of Transportation

- A TMA Truck is used to protect the mobile work zone when putting paint on the highway

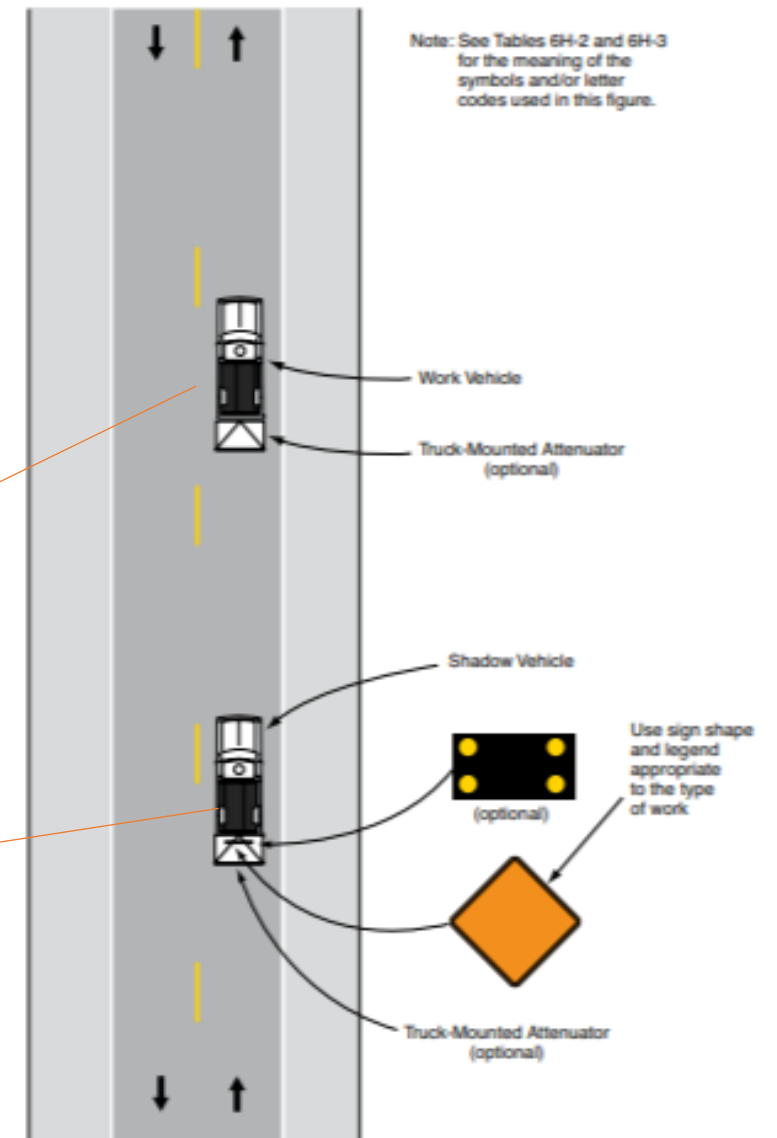


# Traffic Mobile Attenuator

- Standard Diagrams from ATTSA for shadow vehicles to protect the workers and slow moving vehicles



**Figure 4. Mobile Operations on Two-Lane Road  
(Typical Application-17)**

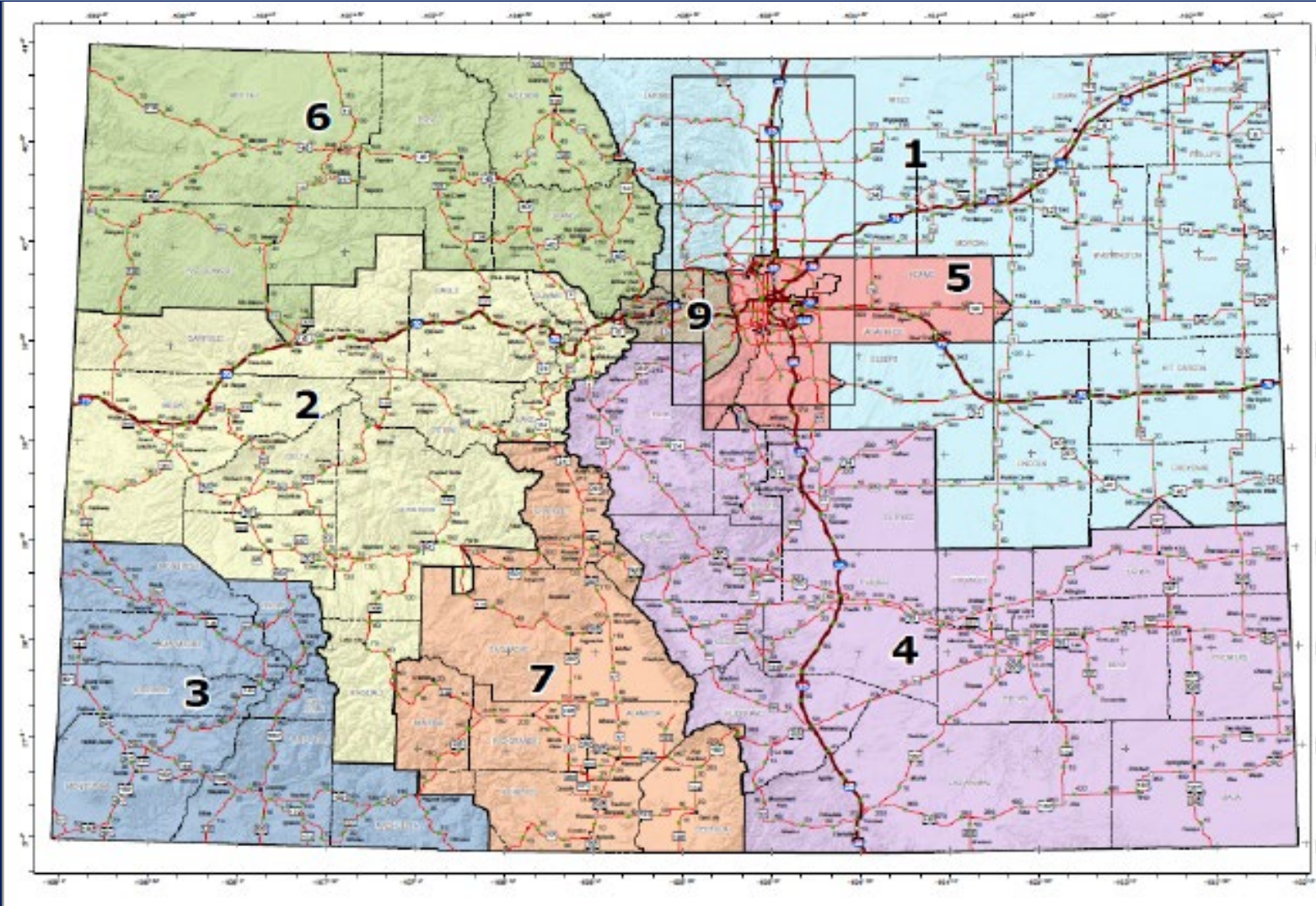


**Typical Application 17**

# Where We Operate



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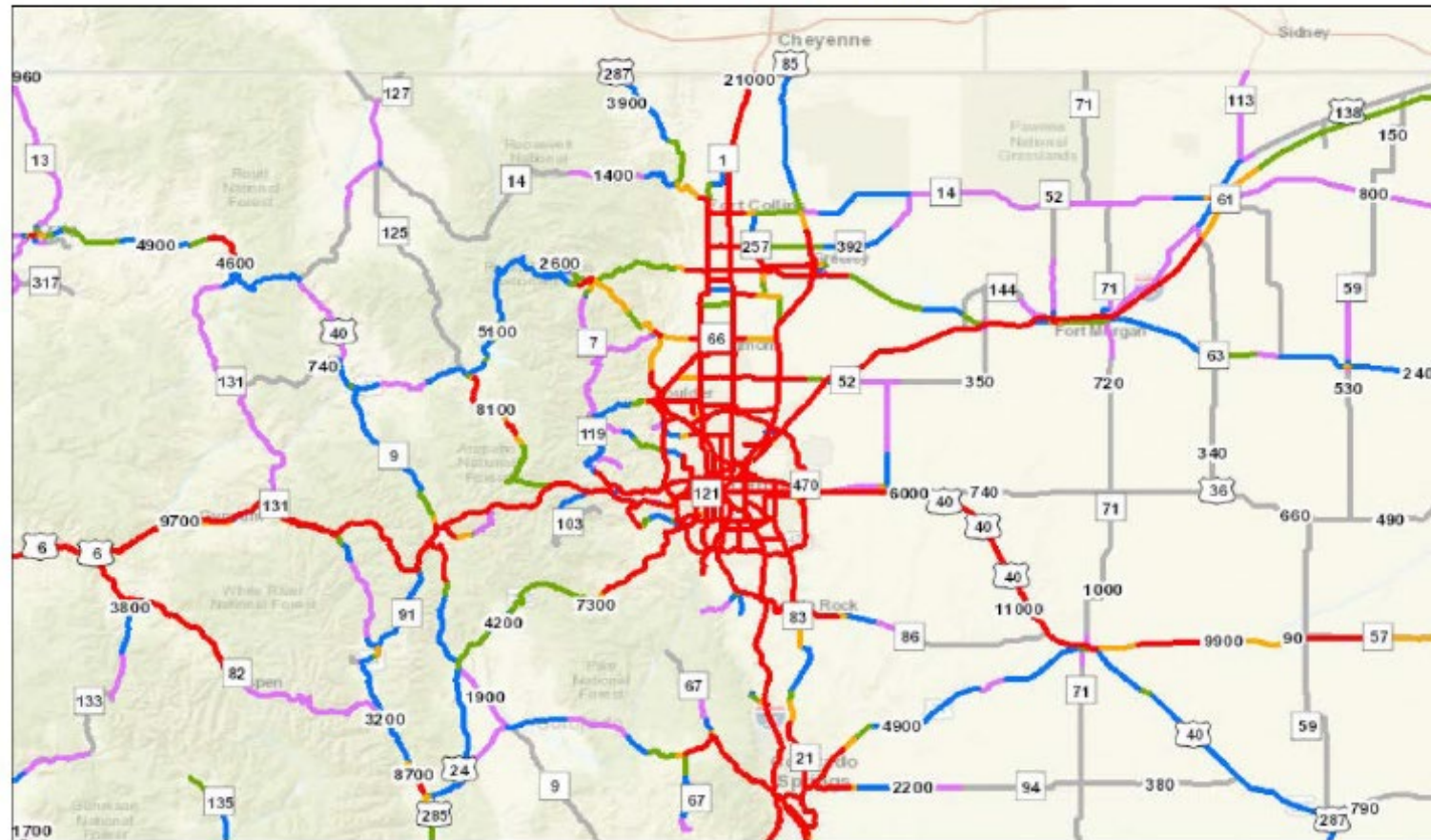
CDOT ATMAs approved for operations on in rural areas of Section 1 and 3 & 7.

# Where We Operate



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Department of Transportation

Traffic Volume on Colorado Highways



CDOT ATMA's approved for operations on **Blue, Purple, and Grey** roadways.

- 27 state highways
- 41 roadway segments



Print date: October 11, 2017

Data source: Colorado Dept of Transportation

The information contained in this map is based on the most currently available data and has been checked for accuracy. CDOT does not guarantee the accuracy of any information presented, is not liable in any respect for any errors or omissions, and is not responsible for determining "fitness for use".

Traffic Count Locations w/ AADT

Short Duration Counter



Continuous Traffic Recorder



Highway AADT

- Less than 1,000
- 1,000 - 2,000
- 2,500 - 5,000
- 5,000 - 7,000
- 7,500 - 10,000
- Over 10,000

0 5 10 20 30 Miles

# How it Works

- ATMA will autonomously follow a leader vehicle
  - Leader transmits position, speed, heading
  - Follower matches leader's movements using steering, throttle, brake actuators



# How it Works



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- ATMA use's similar technology that is used in surveying GPS total station equipment and multiple satellites overhead.



# Retrofit Installation of System



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- Retrofit leader vehicle with
  - Antennas
  - Navigation module
  - Communications module
- CDOT striping truck completed in ½ day

# Installation of System



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- ATMA Follower systems pre-installed
  - Can be retrofitted to existing trucks
  - CDOT purchased truck & technology
- E-Stop Button
- Lead/Follower Controls
- Steering Yoke
- Actuators under passenger seat

# Detection Using Radar



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- Front mounted radar on follower provides obstacle detection
  - Only reacts to obstacles in the path between leader and follower
  - Emergency stops upon obstacle detection



# Performance Evaluation

- CDOT developed a set of scenarios to verify the capabilities
- First week of performance evaluation conducted at Colorado State University
- In 2017, 2018 and 2019



# Performance Evaluation



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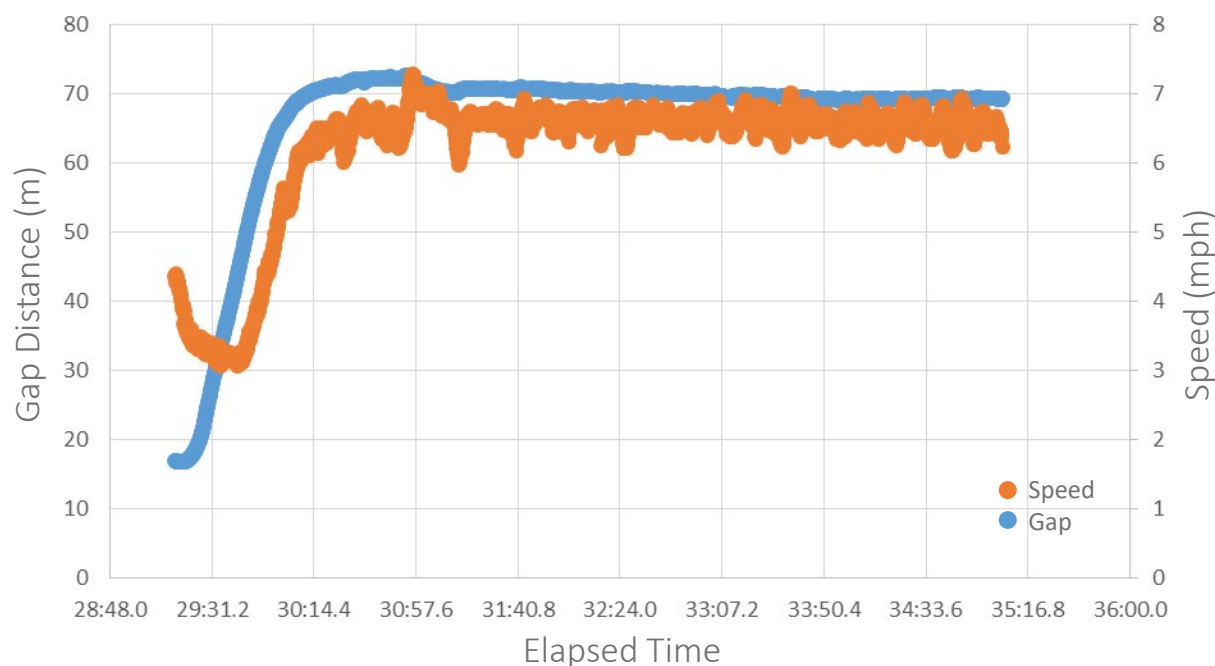
- E-stop Buttons
  - Internal/ External
- Stopping Distance
- Follow Distance
- Lane Accuracy
  - Straight
  - Cornering



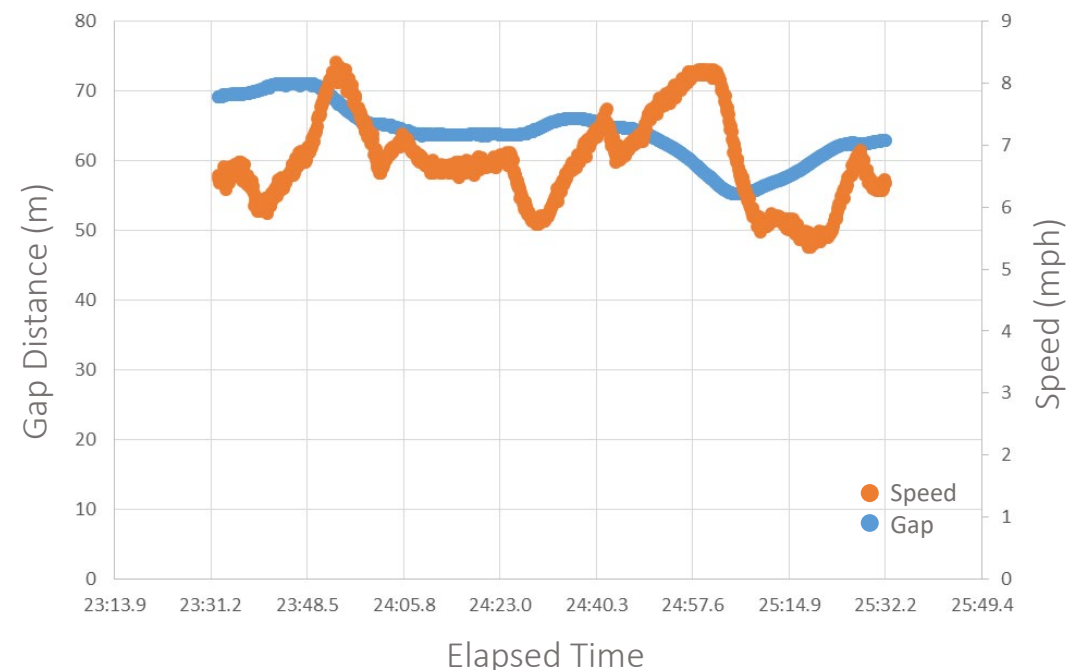
# Gap Control

- Straight line following for 4000' with desired speed 7 mph (striping operation speed) and desired gap 60m
- Recorded gap is measured antenna to antenna: 60m bumper to bumper is 68.89m antenna to antenna

Actual Gap Distance and Speed (Automated System)



Actual Gap Distance and Speed (Human Driver)



# Results



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- Lane accuracy within +/- 4 in
- Gap distance much more consistent than human driver
- Accurate following in cornering and slalom setups
- Performed turns as tight as 45 ft radius
- Identified software and hardware changes to be made

# Colorado Policy - June 2017



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## An Act

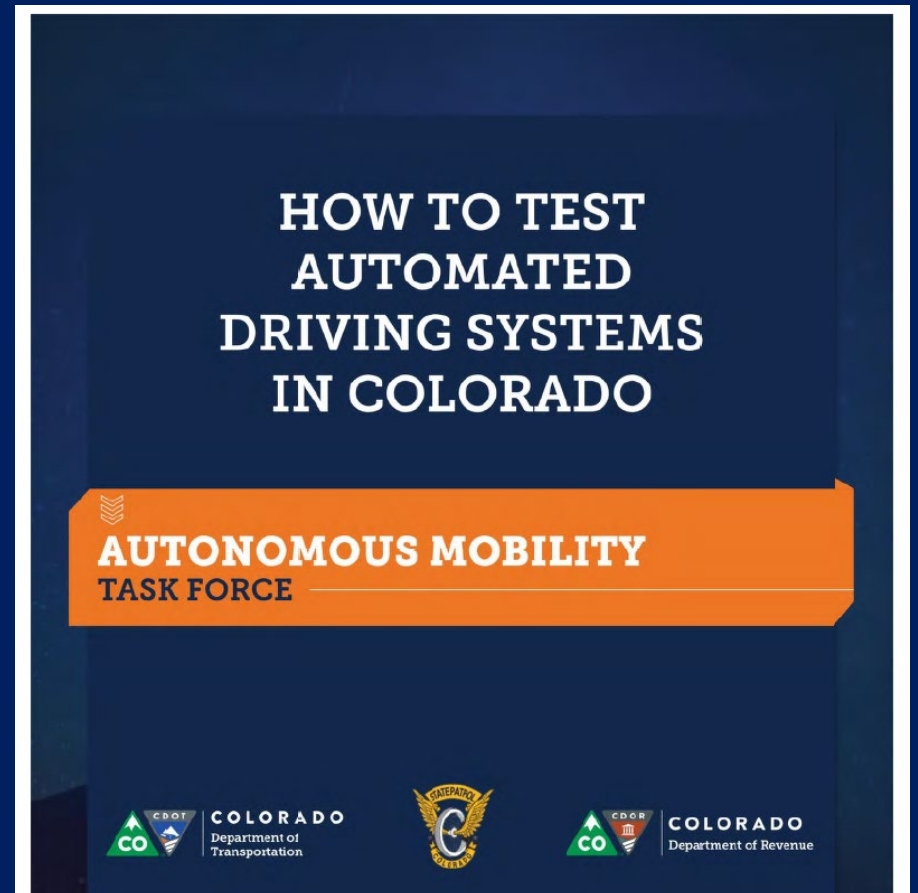
SENATE BILL 17-213

BY SENATOR(S) Hill and Moreno, Baumgardner, Cooke, Crowder, Gardner, Holbert, Lambert, Lundberg, Marble, Smallwood, Tate, Todd, Williams A., Zenzinger, Grantham;  
also REPRESENTATIVE(S) Winter and Bridges, Lundeen, Arndt, Becker K., Buckner, Covarrubias, Garnett, Ginal, Gray, Hansen, Kennedy, Kraft-Tharp, Lawrence, Liston, Melton, Nordberg, Saine, Singer, Valdez, Wist, Young, Coleman, Hooton, Jackson, Michaelson Jenet, Pabon, Sias, Duran.

CONCERNING AUTHORIZATION FOR AUTOMATED DRIVING SYSTEMS TO  
CONTROL MOTOR VEHICLES THROUGHOUT COLORADO.

# Policy and Operational Usage

- Task Force including CDOT & CSP & Revenue to Review
  - Risk, Public Relations, Operations & Policy
- Autonomous CSP & CDOT Process
  1. Operational Domain
  2. Certifications
    1. Safety Assessment
    2. Driver
    3. Vehicle
    4. Insurance
    5. Special Event
  3. Other



# Policy and Operational Usage



## CDOT Ops Plan

- Safety Driver
- Visual Contact
- Linear Operation
- AADT less than 2500
- Less than 10mph



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Department of Transportation  
Division of Highway Maintenance

## Autonomous Truck Mounted Attenuator Operations Plan

### Contents

CDOT Operating Plan .....	2
Scope .....	2
Non-Autonomous Operation .....	2
Autonomous Operation .....	2
Safety Observer .....	2
Authorized Use .....	2
Operating Procedure .....	3
Emergency Stop Conditions .....	3
Crash / Incident Involving ATMA .....	3
Authority and Adoption .....	4

# Autonomous Maintenance Technology

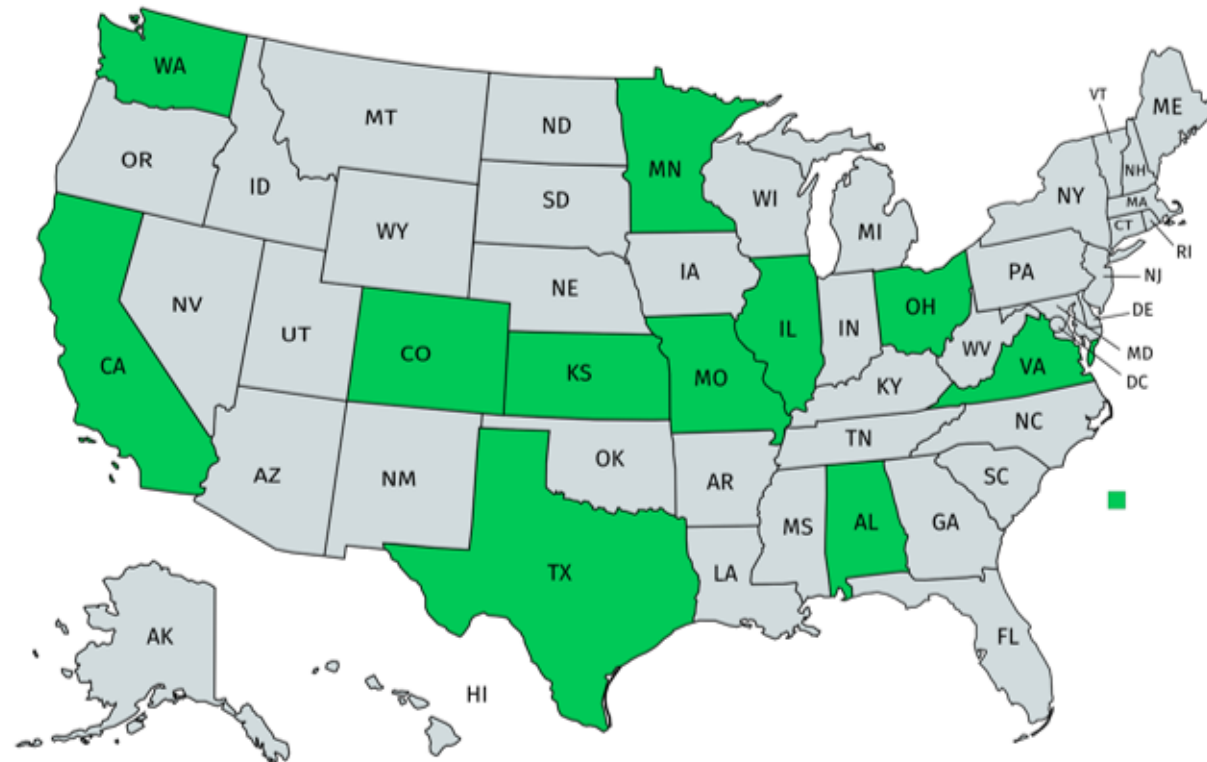


## POOLED FUND PROGRAM PARTICIPATION **11 STATES**

### SCOPE OF WORK

The group will fund research and development efforts to achieve the program goals, with initial proposed research focusing on:

- Improvements on existing ATMA/AIPV platforms (Autonomous Truck Mounted Attenuator/Impact Protection Vehicle)
- Expansion of use of ATMA/AIPV platforms beyond striping  
Refining policy and operational procedures for autonomous work vehicles.
- Investigate additional applications for autonomous vehicles in maintenance operations
- Other New Technology



# Autonomous Maintenance Technology



The mission of this pool study is to develop and deploy ATMA or AIPVs to protect highway worker lives by enhancing cooperative inter-agency research that improves the safety and effectiveness of ATMA or AIPV operations, and to facilitate communication between transportation agencies that encounter challenges with implementation.

Vision Mission Operations Document Sept 2018



AUTONOMOUS MAINTENANCE  
TECHNOLOGY (AMT) POOL  
FUND  
TPF 5(380)  
Vision, Mission, Operations  
Document

Date  
24 September 2018

# Cost and Benefit



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2017 Initial Cost - \$300,000 (included Hino truck and original retro kit)

2019 Cost \$289,00 ( CDOT supplied truck, Next Generation kit, installation in Florida, leader kit installation in Colorado, validation, training and support)

Balance Cost and Safety – What is the cost of one workman compensation claim?

# Thank you



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- CDOT - Presenter
- [tyler.weldon@state.co.us](mailto:tyler.weldon@state.co.us)
- Kratos (Contact)– Maynard Factor
- [mfactor@gomicrosystems.com](mailto:mfactor@gomicrosystems.com)
- Royal Truck and Equipment (Contact)
- Thomas Pucci
  - [tpucci@royaltruckandequipment](mailto:tpucci@royaltruckandequipment)



• <https://www.youtube.com/watch?v=6gKHPG5uOes&t=110s>



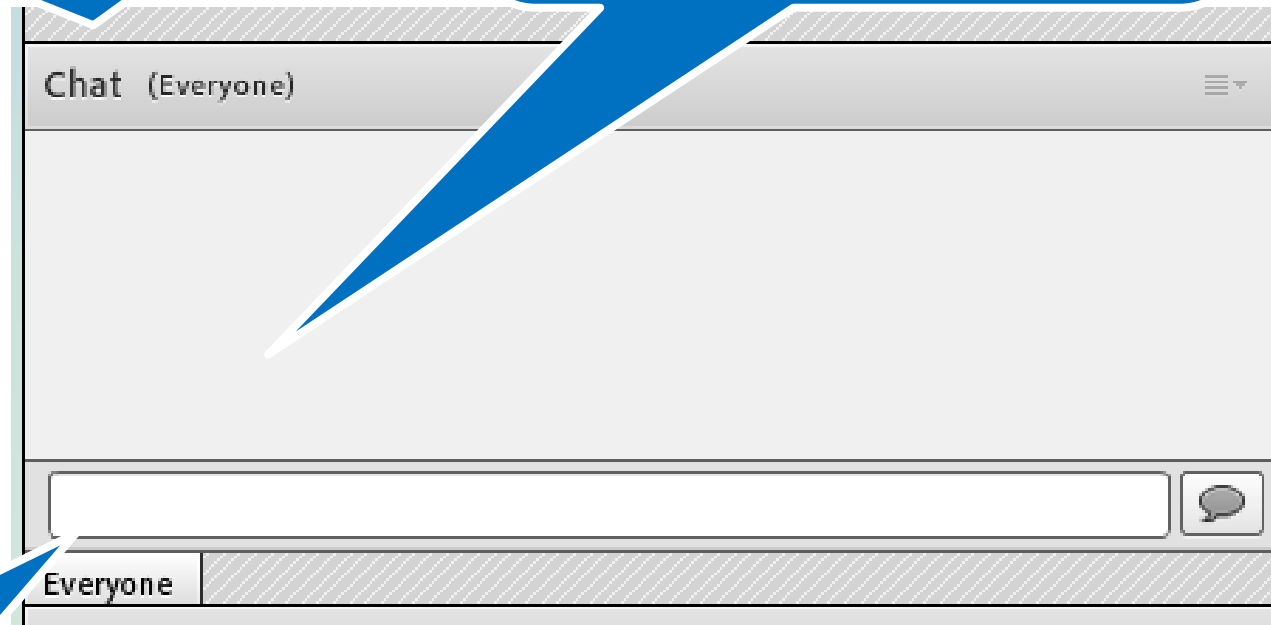


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Randy Johnson  
KC Scout Manager  
Missouri DOT



National  
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Explain how connected and automated vehicles work and list actionable items you can take to prepare for automated, connected, and electric vehicles in rural areas.

Name the benefits of using an autonomous attenuator truck in rural areas.

Define how a real-time digital warning system works.



Randy used a Prezi to present, therefore please refer to the webinar recording to see the information he presented.



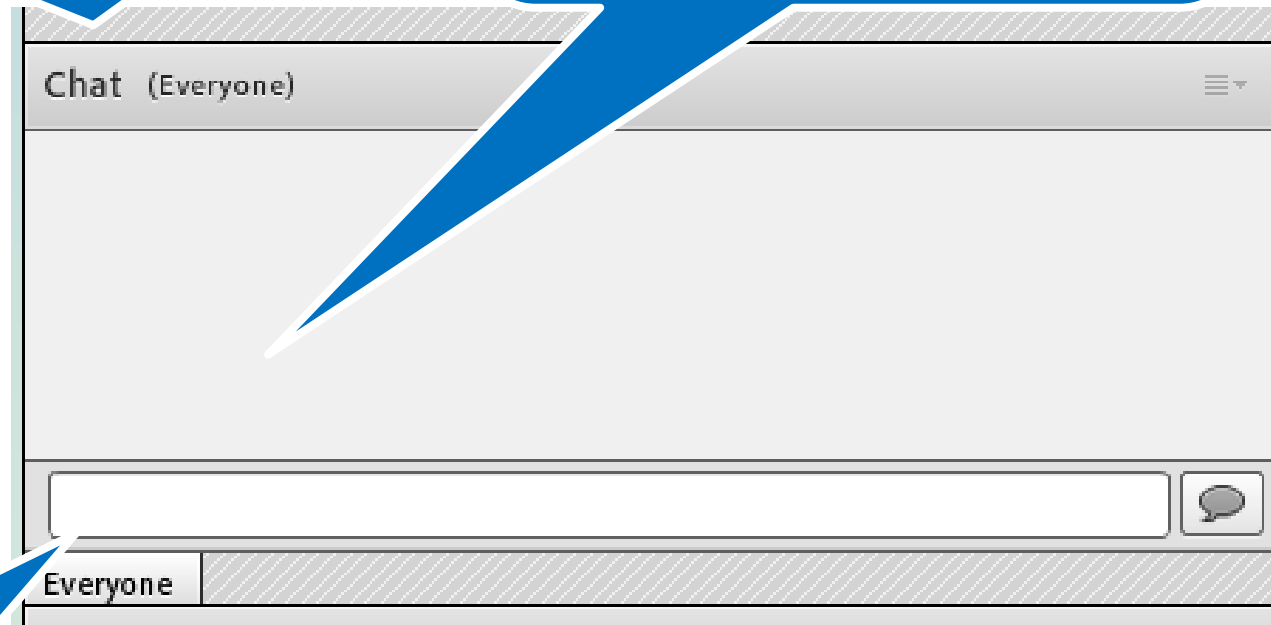


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# Learning Outcomes

To achieve the webinar goal, you have learned to:

Explain how connected and automated vehicles work and list actionable items you can take to prepare for automated, connected, and electric vehicles in rural areas.

Name the benefits of using an autonomous attenuator truck in rural areas.

Define how a real-time digital warning system works.





# New Resources

- **FHWA's 3 Approaches to Safety Video: Site-Specific, Systematic, Systemic**

<https://www.youtube.com/watch?v=1Gtz0qjPx0M>

- **FHWA and ITE's Safe System Strategic Plan**

[https://safety.fhwa.dot.gov/zerodeaths/docs/FHWA-SA-21-088 Safe System Strategic Plan.pdf](https://safety.fhwa.dot.gov/zerodeaths/docs/FHWA-SA-21-088_Safe_System_Strategic_Plan.pdf)

- **RTZ's Doubling Down on What Works**

<https://www.nsc.org/road/resources/road-to-zero/doubling-down-on-what-works>

- **NHTSA's Countermeasures that Work 10<sup>th</sup> Edition**

<https://rosap.nhtl.bts.gov/view/dot/57466>





# Upcoming 2021 Webinars

- Safe System for Rural Areas Webinar Series
  - Part 4: Safe Speeds (Wed. October 27<sup>th</sup> from 1-2:30 PM ET)
  - Part 5: Safe Roads (November)
  - Part 6: Post-Crash Care (December)
- Driving FoRRRwD to Reduce Curve Crashes with Signing and Marking (Wed. Oct. 13<sup>th</sup> from 1:00-3:00 PM ET)
- National Transportation Safety Board's Roundtable Series: Safe Roads (Thurs. Oct. 6 from 1:00-3:00 pm ET)

<https://www.nts.gov/news/events/Pages/2021-safe-systems4-rt.aspx>





# Contact Information

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***Or contact the National Center for Rural Road Safety Help Desk at:***

**(406) 994-7368 or [info@ruralsafetycenter.org](mailto:info@ruralsafetycenter.org)**

**<http://ruralsafetycenter.org/>**

